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Obvious Disparities on Optimal Guesswork Wiretapper Moments under Mismatch Related to Non-Shannon Cypher System

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Author's contribution

The sole author designed, analysed, interpreted and prepared the manuscript.

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Abstract

The invention of several significant non-Shannon entropy inequalities, the optimal Gaussing theorems, the relationship between the discrete memoryless source pair and the probability mass function, and these topics are all covered in the current communication. It may directly or indirectly prove to be significant for the literature of information theory.

Keywords: Optimal guessing function; shannon entropy; predictability; source pair; random variable; inequality.

1 Introduction

Think about the challenge of predicting the value that a discrete random variable, X, assumed in one trial of a random experiment by asking questions of the pattern "Did X take on its i^{th} possible value?" until the response is "yes" In the context of sequential decoding [1] and source-channel coding [2,3,4], as well as in security

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applications [5,6,7,4], the guessing problem has been studied. In the final subsection, we give a summary of earlier work. In 2023, Verma [8,9,10,11] presented the properties of his own generated entropy. Although we do not go into greater detail here, it is also possible to define guessing in the presence of distortion or source uncertainty [2,4,12].

This issue can occur, for example, when a cryptanalyst must test each potential secret key one at a time after cryptanalyzing the possibilities. Let *G* represent the total number of guesses made when using the guessing method that minimizes E(G), which is obviously to guess the potential values of *X* in decreasing order of likelihood. We can assume that these are the first, second, third, etc., conceivable values of *X* without losing the crucial generality, in which case the probability distribution for *X*, say $P = p_1, p_2, \dots$ satisfies $p_1 \ge p_2 \ge \cdots$ and we will refer to such a *P* as a monotone distribution. With this approach, $E(G) = \sum i p_i$, where the summation is on *i* from 1 to infinity in this sum and all subsequent sums.

1.1 Definitions and notation

In this part, we present a few definitions. A method of producing successive questions of the aforementioned kind until a YES response is given is a guessing approach for identifying X. A function $G: X \to \{1, 2, ...\}$ where G(k) equals the time index of the query can be used to express any such method informally. Is X = k?

Keep in mind that legitimate guessing methods' related functions *G* cannot be completely random. Since only one element can be probed at once, it is obvious that *G* must be invertible on its range of $\{1, 2, ...\}$. Additionally, since we presume that the responses to the questions " Is *X* equal to *k*?" are noiseless, it is sufficient to take into account guessing tactics that ask the aforementioned query precisely once for each value of $k \ge 1$. Formally, this is equivalent to the mapping *G* being one-to-one and onto. Any function that meets these two requirements is referred to as a guessing function. A legitimate guessing strategy [13,14] is defined by every guessing function and vice versa.

The guesser is interested in reducing the number of questions needed to identify X, assuming that she is aware of the probability distribution P (otherwise, see [12]). There are various approaches to formalize this objective, such as minimizing a positive moment

$$E(G^{\rho})$$
 (most commonly, $\rho = 1$ is of relevance), where

$$E(G^{\rho}) = \sum_{x \in X} P(x)G(x)^{\rho} = \sum_{k \ge 1} k^{\rho} P(G^{-1}(k))$$

The Renyi entropy of order a of X is a generalization of the Shannon entropy [15] defined by

$$H_{\alpha}(X) = \frac{\log(\sum_{X \in y} P(X)^{\alpha})}{1-\alpha} \quad \forall \ \alpha \in [0, 1) \cup (1, \infty)$$

and obeys $\lim_{\alpha \to 1} H_{\alpha}(X) = H(X)$ as well as being strictly decreasing in α unless the $Y \in y$ is uniform on its support. Sometimes, related random variable $Y \in y$ with some joint distribution P(X, Y) is available to the guesser, who then proceeds to guess the possible value of X as above. In this case,

$$E[G(X|Y)] = \sum_{Y \in v} P(Y)E[G(X|Y = y)].$$

With X taking values in a finite set J of size M and Y taking values in a countable set K, let (X, Y) be a pair of random variables. If $G: J \rightarrow (1, 2, ..., M)$ is one-to-one, we can refer to a function G(X) of the random variable X as a guessing function for X. If, for any fixed number Y = y, a function G(X|Y) is a guessing function for X, then we refer to that function as a guessing function for X given Y. When the value of Y is known, G(X|Y) will be interpreted as the number of guesses necessary to determine X. The moments of G(X) and G(X|Y) are inequalities according to the following [16].

2 Our Claims

Claim 2.1 For any **OGF** (optimal guessing function) $G_P\left(\frac{x}{y}\right)$ and $\tau \ge 0$. Show that the inequality $\frac{1}{2}(\tau + 1) \ln \left[G\left(\frac{x}{y}\right)G_P\left(\frac{x}{y}\right)^{\tau}\right]^2 \le 2(\tau + 1) \ln \sum_{y \in Y} P(y) + 2\ln \sum_{x \in X} P\left(\frac{x}{y}\right) + 2K$, where, *K* is defined by $\tau \ln \sum_{a \in X} P(a/y)$.

Proof: Since the inequality for **OGF** $G_P\left(\frac{X}{Y}\right)$, we have

$$G_P\left(\frac{X}{Y}\right) \leq \sum_{a \in X} \left[\frac{P(a/y)}{P(x/y)}\right]^{\frac{1}{\tau+1}}$$

For the completion of the proof, since

$$\ln E \left[G_P \left(\frac{x}{Y} \right)^{\tau} \right] \le \ln \left[\sum_{y \in Y} P(y) \sum_{x \in X} P \left(\frac{x}{y} \right) G_P \left(\frac{x}{Y} \right)^{\tau} \right]$$

i.e.
$$\ln E^2 \left[G_P \left(\frac{x}{Y} \right)^{\tau} \right] \le \ln \left[\sum_{y \in Y} P(y)^2 \sum_{x \in X} P \left(\frac{x}{y} \right)^2 G_P \left(\frac{x}{Y} \right)^{2\tau} \right]$$

Now, from above discussed equations, we achieve the following result

$$\ln E^{2} \left[G_{P} \left(\frac{x}{y} \right)^{\tau} \right] \leq \ln \sum_{y \in Y} P(y)^{2} + \ln \sum_{x \in X} P \left(\frac{x}{y} \right)^{2} + \ln \sum_{a \in X} \left[\frac{P(a/y)}{P(x/y)} \right]^{\frac{2\tau}{\tau+1}}$$

$$\leq \ln \sum_{y \in Y} P(y)^{2} + \ln \sum_{x \in X} P \left(\frac{x}{y} \right)^{\frac{2}{\tau+1}} + \ln \sum_{a \in X} P(a/y)^{\frac{2\tau}{\tau+1}}$$

$$\leq 2\ln \sum_{y \in Y} P(y) + \frac{2}{\tau+1} \ln \sum_{x \in X} P \left(\frac{x}{y} \right) + \frac{2\tau}{\tau+1} \ln \sum_{a \in X} P(a/y)$$

$$\frac{1}{2} (\tau+1) \ln \left[G \left(\frac{x}{y} \right) G_{P} \left(\frac{x}{y} \right)^{\tau} \right]^{2} \leq 2(\tau+1) \ln \sum_{y \in Y} P(y) + 2\ln \sum_{x \in X} P \left(\frac{x}{y} \right) + 2\tau \ln \sum_{a \in X} P(a/y)$$

$$i.e. \ \frac{1}{2} (\tau+1) \ln \left[G \left(\frac{x}{y} \right) G_{P} \left(\frac{x}{y} \right)^{\tau} \right]^{2} \leq 2(\tau+1) \ln \sum_{y \in Y} P(y) + 2\ln \sum_{x \in X} P \left(\frac{x}{y} \right) + 2K$$

Hence, the inequality.

Claim 2.2 For any **OGF** (optimal guessing function) $G_P\left(\frac{x}{y}\right)$ and $\tau \ge 0$. Show that the inequality $\ln E\left[G_P\left(\frac{x}{y}\right)^{-\epsilon}\right] \le \ln \sum_{y \in Y} P(y) + \frac{1}{-\epsilon+1} \ln \sum_{x \in X} P\left(\frac{x}{y}\right) - R_{\epsilon}(P)$, where $\beta = \frac{1}{2^{1-\alpha}-1}$.

Proof: Since for any **OGF** $G_P\left(\frac{X}{Y}\right)$, we have

$$G_P\left(\frac{x}{Y}\right) \leq \sum_{a \in X} \left[\frac{P(a/y)}{P(x/y)}\right]^{\frac{1}{\tau+1}}$$

We achieve the result as follows

$$\ln E\left[G_P\left(\frac{x}{y}\right)^{\tau}\right] = \ln\left[\sum_{y \in Y} P(y) \sum_{x \in X} P\left(\frac{x}{y}\right) G_P\left(\frac{x}{y}\right)^{\tau}\right]$$

Now, from the above discussed equations, we achieve the following result

$$\ln E\left[G_P\left(\frac{x}{y}\right)^{\tau}\right] \le \ln\left[\sum_{y\in Y} P(y) \sum_{x\in X} P\left(\frac{x}{y}\right) \left[\sum_{a\in X} \left[\frac{P(a/y)}{P(x/y)}\right]^{\frac{1}{\tau+1}}\right]^{\tau}\right]^{\frac{1}{\tau+1}} \le \ln \sum_{y\in Y} P(y) + \ln \sum_{x\in X} P\left(\frac{x}{y}\right)^{\frac{1}{\tau+1}} + \ln\left[\sum_{a\in X} \left[\frac{P(a/y)}{P(x/y)}\right]^{\frac{1}{\tau+1}}\right]^{\tau} \le \ln \sum_{y\in Y} P(y) + \frac{1}{\tau+1} \ln \sum_{x\in X} P\left(\frac{x}{y}\right) + \frac{1}{\tau+1} \ln \sum_{x\in X} P\left(\frac{a}{y}\right)^{\tau}$$

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$$\leq \ln \sum_{y \in Y} P(y) + \frac{1}{\tau + 1} \ln \sum_{x \in X} P\left(\frac{x}{y}\right) + \frac{1}{\tau + 1} \ln \sum_{x \in X} P\left(\frac{a}{y}\right)^{\tau}$$

On replacing τ by – ϵ , we have

$$\leq \ln \sum_{y \in Y} P(y) + \frac{1}{-\epsilon+1} \ln \sum_{x \in X} P\left(\frac{x}{y}\right) + \frac{1}{-\epsilon+1} \ln \sum_{x \in X} P\left(\frac{a}{y}\right)^{-\epsilon}$$

i.e.
$$\ln E\left[G_P\left(\frac{x}{y}\right)^{-\epsilon}\right] \leq \ln \sum_{y \in Y} P(y) + \frac{1}{-\epsilon+1} \ln \sum_{x \in X} P\left(\frac{x}{y}\right) - R_{\epsilon}(P)$$

Hence, the inequality.

Claim 2.3 Let $\tau > 0$. Consider a source pair (X, Y) with PMF *P*. If $\nu = \frac{1}{1+\tau}$ then $\frac{H^{\alpha}(P)}{(1+\ln X)^{\tau}}$ is less than or equal to

$$\frac{1}{2^{1-\nu}-1}\sum_{x\in X}\sum_{y\in Y}\left[P(x,y)\left(\sum_{a\in X}P(a,y)^{\frac{1}{1+\tau}}\right)^{\tau}-\sum_{x\in X}\left(P(x,y)^{\frac{1}{1+\tau}}\right)^{\tau}\right]\left[\sum_{x\in X}\left(P(x,y)^{\frac{1}{1+\tau}}\right)^{\tau}\right]^{-1}$$

and in particular, $\nu = \frac{1}{2}$ then, $\frac{H^{\alpha}(P)}{(1+\ln X)^{\tau}}$ is less than or equal to

$$\frac{1}{\sqrt{2}-1} \cdot \sum_{x \in X} \sum_{y \in Y} \left[P(x,y) \left(\sum_{a \in X} P(a,y)^{\frac{1}{1+\tau}} \right)^{\tau} - \sum_{x \in X} \left(P(x,y)^{\frac{1}{1+\tau}} \right)^{\tau} \right] \left[\sum_{x \in X} \left(P(x,y)^{\frac{1}{1+\tau}} \right)^{\tau} \right]^{-1}.$$

Proof: The inequality for OGF is

$$\frac{H^{\nu}(P)}{\lambda} + 1 \ge E(G_P(X,Y)^{\tau})$$

and $H^{\nu}(P) \ge \frac{H^{\nu}(P)}{(1+\ln X)^{\tau}}$
So, $\frac{H^{\nu}(P)}{(1+\ln X)^{\rho}} = \lambda [E(G_P(X,Y)^{\tau}) - 1]$
 $= \lambda [\sum_{y \in Y} \sum_{x \in X} p(x,y)G_P(x,y)^{\tau} - 1]$

For $\tau > 0$ and each $y \in Y$

$$\sum_{a \in X} \left(\frac{P(a, y)}{P(x, y)} \right)^{\frac{1}{1+\tau}} \ge G_P(x, y)$$

Now, $\lambda \left[\sum_{y \in Y} \sum_{x \in X} P(x, y) G_P(x, y)^{\tau} - 1 \right]$

$$\leq \lambda \left[\sum_{y \in Y} \sum_{x \in X} P(x, y) \left(\sum_{a \in X} \left(\frac{P(a, y)}{P(x, y)} \right)^{\frac{1}{1+\tau}} \right)^{\tau} - 1 \right]$$

$$\leq \lambda \left[\sum_{y \in Y} \sum_{x \in X} \frac{P(x, y) \left(\sum_{a \in X} P(a, y)^{\frac{1}{1+\tau}} \right)^{\tau} - \sum_{x \in X} \left(P(x, y)^{\frac{1}{1+\tau}} \right)^{\tau}}{\sum_{x \in X} \left(P(x, y)^{\frac{1}{1+\tau}} \right)^{\tau}} \right]$$

$$\leq \lambda \sum_{x \in X} \sum_{y \in Y} \left[P(x, y) \left(\sum_{a \in X} P(a, y)^{\frac{1}{1+\tau}} \right)^{\tau} - \sum_{x \in X} \left(P(x, y)^{\frac{1}{1+\tau}} \right)^{\tau} \right] \left[\sum_{x \in X} \left(P(x, y)^{\frac{1}{1+\tau}} \right)^{\tau} \right]^{-1}$$

Setting, $\lambda = \frac{1}{2^{1-\nu}-1}$. Hence, $\frac{H^{\nu}(P)}{(1+\ln X)^{\tau}}$ is less than or equal to

$$\frac{1}{2^{1-\nu}-1} \sum_{x \in X} \sum_{y \in Y} \left[P(x,y) \left(\sum_{a \in X} P(a,y)^{\frac{1}{1+\tau}} \right)^{\tau} - \sum_{x \in X} \left(P(x,y)^{\frac{1}{1+\tau}} \right)^{\tau} \right] \left[\sum_{x \in X} \left(P(x,y)^{\frac{1}{1+\tau}} \right)^{\tau} \right]^{-1}$$

and in particular, $\nu = \frac{1}{2}$ then, $\frac{H^{\frac{1}{2}}(P)}{(1+\ln X)^{\tau}} \le \frac{1}{\sqrt{2}-1} \cdot \sum_{x \in X} \sum_{y \in Y} \left[P(x,y) \left(\sum_{a \in X} P(a,y)^{\frac{1}{1+\tau}} \right)^{\tau} - \sum_{x \in X} \left(P(x,y)^{\frac{1}{1+\tau}} \right)^{\tau} \right] \left[\sum_{x \in X} \left(P(x,y)^{\frac{1}{1+\tau}} \right)^{\tau} \right]^{-1}.$

Hence, the required inequality.

3 Conclusion

We developed an entirely novel and explicit accurate characterisation of the expected number of guesses for a single attacker in the unrestricted attacker case in terms of Renyi entropy. Another new result obtained in the paper is Claim 2.3, an interesting derivation of the union bound which is widely used in information theory, in terms of the expected number of guesses in a conditional guessing scheme which takes the output of a communication channel as its input.

Competing Interests

Author has declared that no competing interests exist.

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